

Representations of G and $L^1(G)$

INTRODUCTION: This note was motivated by lectures by Gabriel Nagy at Kansas State. We refer frequently to D&E, which refers to *Principles of Harmonic Analysis* by Anton Deitmar and Siegfried Echterhoff (Springer 2009). We also refer to H&R, this being volumes 1 and 2 of Hewitt & Ross's *Abstract Harmonic Analysis*. Observe that a version of Theorem 1 below is in H&R, 22.10 and 22.7, but that its proof is much too complicated. It uses the fact (21.13) that every $*$ -representation on a Hilbert space is a direct sum of cyclic subrepresentations.

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This is about “duality” between norm-continuous representations π of the algebra $L^1(G)$ by bounded linear operators $\mathcal{B}(V)$, V a Banach space, and bounded continuous group representations U_x of G on V . Here G is an LC-group with left Haar measure μ . One direction is, of course, easy: From U_x one builds π by

$$\pi(f)v := \int_G f(x)U_x(v)d\mu(x) \quad \text{for } f \in L^1(G), v \in V, \quad (0)$$

a V -valued integral. Let (e_j) be a nice approximate identity which D&E call a Dirac net. As noted in D&E 6.2.2, $\lim_j \pi(e_j)v = v$ for all $v \in V$. In other words, the net of operators $\pi(e_j)$ on V converges to the identity operator on V in the strong operator topology.

Now we begin with an algebra representation π of $A = L^1(G)$ satisfying for some finite $C \geq 1$,

$$\|\pi(f)\|_{op} \leq C \|f\|_1 \quad \text{for } f \in L^1(G). \quad (1)$$

Following D&E (and Nagy), we say that π is **non-degenerate** if

$$\pi(A)V = \{\pi(f)v : f \in L^1(G), v \in V\} \quad \text{spans a dense subspace of } V, \quad (2)$$

where $\pi(A)V = \{\pi(f)v : f \in L^1(G), v \in V\}$. (If V is a Hilbert space and π is a $*$ -representation, then (2) is plainly the same as saying $\pi(f)(v) = 0$ for all $f \in L^1(G)$ implies $v = 0$.)

Lemma 1. If π is non-degenerate as above, then $\pi(A)V = V$.

Proof. We define $(f, v) \rightarrow f \bullet v$ from $A = L^1(G) \times V \rightarrow V$, where $f \bullet v = \pi(f)v$. Then V is a Banach $L^1(G)$ -module (H&R 32.14). In particular, $(f * g) \bullet v = \pi(f * g)v = \pi(f)(\pi(g)v) = f \bullet (\pi(g)v) = f \bullet (g \bullet v)$ and

$$\|f \bullet v\| = \|\pi(f)v\| \leq \|\pi(f)\|_{op} \cdot \|v\| \leq C \|f\|_1 \cdot \|v\|.$$

The Dirac net (e_j) is a bounded approximate unit for $L^1(G)$, so the Cohen Factorization Theorem (H&R 32.22) tells us that $\pi(A)V = A \bullet V$ is a closed linear subspace of V , and thus $\pi(A)V = V$. $\square$

For Lemma 2 and Theorem 1 below, we will give two proofs, one using Lemma 1 and the other not.

Lemma 2. If π is non-degenerate, then $\lim_j \pi(e_j)v = v$ for all $v \in V$.

Proof using Lemma 1. Given $v \in V$, we have $v = \pi(f)w = f \bullet w$ for some $f \in L^1(G)$ and $w \in V$. Therefore

$$\lim_j \pi(e_j)v = \lim_j e_j \bullet w = \lim_j e_j \bullet (f \bullet w) = \lim_j (e_j * f) \bullet w = f \bullet w = v. \quad \square$$

Proof avoiding Lemma 1. Given $v \in V$ and $\epsilon > 0$, use (2) to select $\sum_{i=1}^n \pi(f_i)v_i$ satisfying

$$\left\| \sum_{i=1}^n \pi(f_i)v_i - v \right\| < \frac{\epsilon}{3C}.$$

Then $\|\pi(e_j)v - v\|$ is bounded by

$$\left\| \pi(e_j)v - \sum_{i=1}^n \pi(e_j)\pi(f_i)v_i \right\| + \left\| \sum_{i=1}^n \pi(e_j)\pi(f_i)v_i - \sum_{i=1}^n \pi(f_i)v_i \right\| + \left\| \sum_{i=1}^n \pi(f_i)v_i - v \right\|.$$

The third and first terms in the sum are bounded by $\epsilon/3$, and the middle term is bounded by

$$\sum_{i=1}^n \|\pi(e_j * f_i - f_i)v_i\| \leq C \sum_{i=1}^n \|e_j * f_i - f_i\|_1 \cdot \|v_i\|,$$

which is also less than $\epsilon/3$ for sufficiently “large” j in the Dirac net. $\square$

NOTE. Thus, for non-degenerate π : if $\pi(f)v = 0$ for all $f \in L^1(G)$, then $v = 0$. This is the non-degeneracy-like hypothesis in H&R 22.10 and 22.7.

Theorem 1. Given a norm-continuous representation π of $A = L^1(G)$, as described above, there exists a representation U_x of G , where each U_x is a bounded linear operator on V with norm not greater than C , and such that equation (0) holds.

Proof using Lemma 1. For $x \in G$, we propose to define $U_x : V \rightarrow V$ by

$$U_x(\pi(f)v) := \pi(L_x(f))v \quad \text{for all } x \in G \text{ and } f \in L^1(G), \quad (3)$$

where L_x is left translation by x^{-1} in $L^1(G)$. Since $V = \pi(A)V$, U_x is defined for all $v \in V$, provided that it is well-defined. But note that

$$\pi(L_x(e_j))(\pi(f)v) = \pi(L_x(e_j) * f)v = \pi(L_x(e_j * f))v \rightarrow \pi(L_x f)v,$$

since π is continuous and $e_j * f \rightarrow f$ in $L^1(G)$. So the right side of (3) is unambiguously determined by the vector $\pi(f)v$. This calculation also shows

$$\|U_x(\pi(f)v)\| \leq \liminf_j \|\pi(L_x(e_j))\|_{op} \cdot \|\pi(f)v\| \leq C \liminf_j \|L_x(e_j)\|_1 \cdot \|\pi(f)v\| = C \|\pi(f)v\|.$$

It remains to verify equation (0): $\pi(f)v = \int_G f(x)U_x(v)d\mu(x)$. For fixed f , both sides are continuous linear functions of v , so it suffices to verify (0) for elements $\pi(g)v$ in $\pi(A)V = V$.

So we want

$$\pi(f)(\pi(g)v) = \int_G f(x)U_x(\pi(g)v)d\mu(x).$$

For fixed v , both sides are continuous as functions of f , so it suffices to consider f in $C_c(G)$. Now we're done:

$$\int_G f(x) U_x(\pi(g)v) d\mu(x) = \int_G f(x) \pi(L_x(g))v d\mu(x) = \int_G \pi(f(x)L_x(g))v d\mu(x),$$

and, as elaborated on in the next paragraph, by D&E B.6.1(c) this is equal to

$$\pi \left(\int_G f(x) L_x(g) d\mu(x) \right) v = \pi(f * g)v = \pi(f)(\pi(g)v),$$

where the first equality follows from D&E B.6.5. Note that $f * g(y) = \int_G f(x)g(x^{-1}y) d\mu(x) = \int_G f(x)L_x(g)(y) d\mu(x)$.

To apply D&E B.6.1(c) above, let $\varphi(x) := f(x)L_x(g)$, so that $\varphi : G \rightarrow L^1(G)$ and we want

$$\int_G \pi(\varphi(x))v d\mu(x) = \pi \left(\int_G \varphi(x) d\mu(x) \right) (v). \quad (4)$$

As noted in the first paragraph of the proof of D&E B.6.5, φ is continuous with compact support. So is the function $x \rightarrow \pi(\varphi(x))v$ from G into V , so both integrals in (5) exist. Now, fix v . Then $T(f) = \pi(f)v$ clearly defines a continuous linear operator $T : L^1(G) \rightarrow V$, and we can apply D&E to φ to obtain $\pi \left(\int_G \varphi(x) d\mu(x) \right) v =$

$$T \left(\int_G \varphi(x) d\mu(x) \right) = \int_G (T(\varphi))(x) d\mu(x) = \int_G T(\varphi(x)) d\mu(x) = \int_G \pi(\varphi(x))v d\mu(x),$$

which is equation (4). $\square$

Proof avoiding Lemma 1. For $x \in G$, we want U_x to satisfy $U_x(\pi(f)v) = \pi(L_x(f))v$ for $f \in A = L^1(G)$ and $v \in V$, where L_x is left translation by x^{-1} in $L^1(G)$. So we first define U_x on the span of $\pi(A)V$:

$$U_x \left(\sum_{i=1}^n \pi(f_i)v_i \right) := \sum_{i=1}^n \pi(L_x(f_i))v_i. \quad (5)$$

Since left translation satisfies $L_x(e) * f = L_x(e * f)$ (H&R 20.11), elements of our Dirac net (e_j) satisfy

$$\pi(L_x(e_j)) \left(\sum_{i=1}^n \pi(f_i)v_i \right) = \sum_{i=1}^n \pi(L_x(e_j) * f_i)v_i = \sum_{i=1}^n \pi(L_x(e_j * e_i))v_i.$$

Since (e_j) is an approximate unit in $L^1(G)$, and L_x and π are continuous, we see that

$$\lim_j \pi(L_x(e_j)) \left(\sum_{i=1}^n \pi(f_i)v_i \right) = \lim_j \sum_{i=1}^n \pi(L_x(e_j * e_i))v_i = \sum_{i=1}^n \pi(L_x(f_i))v_i. \quad (6)$$

Since the left-hand side of (6) depends only on $\sum_{i=1}^n \pi(f_i)v_i$, this shows that definition (5) is well defined.

Equation (6) implies that

$$\left\| \sum_{i=1}^n \pi(L_x(f_i))v_i \right\| \leq \liminf_j \left\| \pi(L_x(e_j)) \right\|_{op} \cdot \left\| \sum_{i=1}^n \pi(f_i)v_i \right\| .$$

Since $\|L_x\|_{op} = 1$ and $\|\pi\| \leq C$, we conclude that

$$\left\| U_x \left(\sum_{i=1}^n \pi(f_i)v_i \right) \right\| \leq C \left\| \sum_{i=1}^n \pi(f_i)v_i \right\| .$$

Thus U_x is a bounded linear operator on the span of $\pi(A)V$, with norm no greater than C . So each U_x can be extended to an operator on V , with norm no greater than C .

The rest of the proof, verifying equation (0), is the same as the Proof using Lemma 1. $\square$

Here is D&E's 6.2.3.

Theorem 2. If π in Theorem 1 is a $*$ -representation on $L^1(G)$, acting on a Hilbert space V , then the representation U on G is a unitary representation.

Proof. This follows from the computation at the bottom of D&E's page 133 together with Lemma 1. $\square$

References:

[D&E] Anton Deitmar and Siegfried Echterhoff, *Principles of Harmonic Analysis*, Springer Science-Business Media, LLC 2009.

[H&R] Edwin Hewitt and Kenneth A. Ross, *Abstract Harmonic Analysis*, Springer-Verlag, volumes I (2nd edition, 1979) and II (1970).