

MATH 432/532 SPRING 2017
HOMEWORK 9
DUE MARCH 10, 2017.
INSTRUCTOR: ROBERT LIPSHITZ

Problems:

- (1) Let $M = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 - z^2 = 1\}$.
 - (a) Prove that M is a smooth submanifold of $\mathbb{R}^3$.
 - (b) For each $p \in M$, describe $T_p M$ as a subspace of $\mathbb{R}^3$.
 - (c) Prove that TM is trivial, i.e., find a smooth map $F: TM \rightarrow M \times \mathbb{R}^2$ so that for all $p \in M$, $F(T_p M) = \{p\} \times \mathbb{R}^2$ and $F|_{T_p M}$ is a vector space isomorphism.
- (2) Lee, Problem 5-11.
- (3) Lee, Problem 5-17.
- (4) Let P_2 denote the vector space of polynomials of degree ≤ 2 . Define $F: P_2 \rightarrow P_2$ by

$$F(p(t)) = p'(t)^2 - 2p(t)p''(t).$$

- (a) Compute the total derivative of F .
 - (b) Observe that $F(1 + 2t + t^2) = 0$. Is 0 a regular value of F ?
- (5) Lee, Problem 15-3. (Ignore the book's hint. Identify $T_p S^n$ with a subspace of $\mathbb{R}^{n+1}$. If $\{v_1, \dots, v_n\}$ is a basis for $T_p S^n$ then $\{p, v_1, \dots, v_n\}$ is a basis for $\mathbb{R}^{n+1}$. Define $[v_1, \dots, v_n]$ to be positively oriented if and only if $[p, v_1, \dots, v_n]$ is a positively oriented basis for $\mathbb{R}^{n+1}$; this is the "outward-normal first" convention. Check that this defines an orientation for S^n , and then think about what the antipodal map does.)

Challenge problems (required for Math 532, optional for 432):

- (6) A *Lie group* is a smooth manifold G with a smooth map $m: G \times G \rightarrow G$ so that which makes G into a group, i.e., which is associative and has an identity element and inverses.
 - (a) Prove that matrix multiplication makes $O(n)$ into a Lie group. (Hint: you did most of the work already.)
 - (b) Prove that $O(n)$ is compact. (Hint: use the Heine-Borel theorem.)
 - (c) Describe $T_I O(n)$, the tangent space at the identity to $O(n)$, as explicitly as you can. (This is the *Lie algebra* of $O(n)$.)
- (7) Prove that if G is an n -dimensional Lie group then the tangent bundle to G is trivial, i.e., there is a smooth map $\phi: G \times \mathbb{R}^n \rightarrow TG$ with the properties that:
 - (a) The map ϕ commutes with the projections $\pi: TG \rightarrow G$ and $\pi': G \times \mathbb{R}^n \rightarrow G$.
 - (b) The map ϕ respects vector addition and scalar multiplication, in the sense that for $v, w \in \mathbb{R}^n$ and $\lambda \in \mathbb{R}$, $\phi(p, v + \lambda w) = \phi(p, v) + \lambda \phi(p, w) \in T_p G$.

(Hint: this is easier than it sounds. Use the differential of the map $L_g: G \rightarrow G$, $L_g(h) = gh$ to identify T_gG with T_eG (where e is the identity element).)

- (8) Prove that $U(n)$, the group of $n \times n$ unitary matrices, and $SU(n)$, the group of $n \times n$ unitary matrices with determinant 1, are Lie groups.
- (9) Prove that $SU(2)$ is diffeomorphic to S^3 , and conclude that TS^3 is trivial. (Hint: $SU(2)$ acts on the unit sphere in $\mathbb{C}^2$. Choose a point $v \in S^3$ and define a map $SU(2) \rightarrow S^3$ by $A \mapsto Av$. Prove that this map is bijective. Check that the differential gives an isomorphism $T_I SU(2) \rightarrow T_v S^3$ and use the Lie group structure to deduce that the differential is an isomorphism at all points in $SU(2)$.)

Optional practice (not required for anyone):

- (10) Lee, Problem 5-1.
- (11) Lee, Problem 5-7.
- (12) Lee, Problem 5-10.
- (13) Lee, Problem 15-12.

Email address: lipshitz@uoregon.edu