

1.4.3 Lorentz transformations of fields

Consider static and homogeneous fields $\mathbf{E}$ and $\mathbf{B}$ that are not parallel to one another in some inertial frame.

- a) Show that there exists an inertial frame in which $\mathbf{E}$ and $\mathbf{B}$ are parallel, and that the two frames are related by a Lorentz boost whose velocity is given by the solution of the equation

$$\frac{\mathbf{V}}{c} (\mathbf{E}^2 + \mathbf{B}^2) = (1 + \mathbf{V}^2/c^2) \mathbf{E} \times \mathbf{B}$$

- b) Show explicitly that this equation has one and only one physical solution that obeys $|\mathbf{V}|/c < 1$, that there always is a physical solution, and that the result in the limit of almost parallel fields in the original reference frame is sensible.
- c) Are there other inertial frames in which $\mathbf{E}$ and $\mathbf{B}$ are parallel? If so, how many?

(7 points)

1.4.3.) a) Let the non-parallel vectors $\vec{E}, \vec{D}$ lie in the y - z -plane:

$$\vec{E} = (0, E_y, E_z), \quad \vec{D} = (0, D_y, D_z)$$

Now consider a Lorentz boost in the x -direction

cf § 4.2 $\rightarrow \tilde{E}_x = E_x = 0$ and $\tilde{D}_x = D_x = 0$.

$$\rightarrow \tilde{\vec{E}} = (0, \tilde{E}_y, \tilde{E}_z), \quad \tilde{\vec{D}} = (0, \tilde{D}_y, \tilde{D}_z)$$

$$\rightarrow \tilde{\vec{E}} \times \tilde{\vec{D}} = (\tilde{E}_y \tilde{D}_z - \tilde{E}_z \tilde{D}_y, 0, 0)$$

$$\rightarrow \tilde{\vec{E}} \parallel \tilde{\vec{D}} \quad \text{iff} \quad \tilde{E}_y \tilde{D}_z - \tilde{E}_z \tilde{D}_y = 0$$

cf § 4.2 $\rightarrow$

$$\begin{aligned} 0 &= (E_y \cos\phi + D_z \sin\phi)(D_z \cos\phi + E_y \sin\phi) - (E_z \cos\phi - D_y \sin\phi)(D_y \cos\phi - E_z \sin\phi) \\ &= (E_y D_z - E_z D_y)(\cos^2\phi + \sin^2\phi) + (E_y^2 + E_z^2 + D_y^2 + D_z^2) \cos\phi \sin\phi \end{aligned}$$

$$\stackrel{\S 4.1}{=} \gamma^2 (1 + \Lambda^2) (\vec{E} \times \vec{D})_x + \gamma' \Lambda (\vec{E}' \cdot \vec{D}') \quad \text{where } \Lambda = v/c$$

If we make the orientation of the plane defined by $\vec{E}$ and $\vec{D}$ arbitrary, then $\vec{V}$ is given by the relation of

$$\frac{\vec{V}}{c} (\vec{E}' \cdot \vec{D}') = (1 + \vec{V}'/c') \vec{E} \times \vec{D}$$

b) Now return to the original geometry and denote

$$(\vec{E} \times \vec{D})_x =: X, \quad \vec{E}' \cdot \vec{D}' =: S, \quad V_x =: V$$

$$\rightarrow X \Lambda^2 - S \Lambda + X = 0$$

$$\rightarrow \underline{\underline{\Lambda = \frac{1}{2x} \left(1 \pm \sqrt{1-4x^2} \right)}} \quad (*)$$

Now consider $\underline{1-4x^2 = (E^2+Q^2)^2 - 4E^2Q^2}$ $x = \frac{1}{2}(\vec{E}, \vec{Q})$

$$\geq (E^2+Q^2)^2 - 4E^2Q^2$$

$$= (E^2-Q^2)^2 \geq 0 \quad (+)$$

$$\rightarrow \underline{\sqrt{1-4x^2}} \in \mathbb{R} \text{ always}$$

$$\rightarrow \underline{\text{there always is at least one solution}}$$

$$\text{that } (+) \rightarrow \left(\frac{1}{2x} \right)^2 \geq 1$$

$$\text{let } x > 0 \text{ w.l.g.} \rightarrow \frac{1}{2x} > 1$$

$$\rightarrow \frac{1}{2x} + \frac{1}{2x} \sqrt{1-4x^2} > 1$$

$$\rightarrow \text{The only candidate for a physical solution is}$$

$$\underline{\underline{\Lambda = \frac{1}{2x} \left(1 - \sqrt{1-4x^2} \right) = \frac{1}{2x} - \sqrt{\left(\frac{1}{2x} \right)^2 - 1}}}$$

$$\text{we still need to show that this solution obeys } \Lambda < 1.$$

$$\text{define } x := \frac{1}{2x} > 0 \text{ w.l.g.}$$

$$\text{then we know } \underline{x > 1}.$$

$$\text{Now demand } x - \sqrt{x^2 - 1} < 1$$

$$\Leftrightarrow x-1 < \sqrt{x^2-1} \Leftrightarrow (x-1)^2 < x^2-1 \Leftrightarrow -2x+1 < -1$$

$$\Leftrightarrow x > 1 \quad \checkmark$$

$$\rightarrow \underline{\underline{\Lambda = x - \sqrt{x^2 - 1}}} \text{ where } \underline{x = \frac{1}{2x} = \frac{E^2+Q^2}{2|\vec{E} \times \vec{Q}|}}$$

is the unique physical solution which always exists

with almost parallel fields $\rightarrow \vec{E} \times \vec{B} \rightarrow 0 \rightarrow \alpha \rightarrow \infty$

$$\rightarrow \underline{\underline{\Delta \rightarrow \alpha - \alpha \sqrt{1 - 1/\alpha^2} = \alpha - \alpha + \frac{1}{2\alpha} + O(1/\alpha^2) = \frac{1}{2\alpha} + O(1/\alpha^2) \rightarrow 0}}$$

which is useful: If the fields are almost parallel to start with, then a small boost velocity w/pins to make them parallel.

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c) Once $\vec{E} \parallel \vec{B}$, e.g., $\vec{E} = (E_x, 0, 0)$, $\vec{B} = (B_x, 0, 0)$ w.d.g.,

then any Lorentz boost in the common direction of $\vec{E}$ and $\vec{B}$

will leave $\vec{E} \parallel \vec{B} \rightarrow$ then an infinitely many rest inertial frames

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